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*Published in:*

Proceedings of the 38th international conference on Software Engineering

*DOI:*

[10.1145/2884781.2884821](https://doi.org/10.1145/2884781.2884821)

*Publication date:*

2016

*Document Version*

Peer reviewed version

[Link to publication](#)

*Citation for pulished version (HARVARD):*

Devroey, X, Perrouin, G, Papadakis, M, Legay, A, Schobbens, P & Heymans, P 2016, Featured Model-based Mutation Analysis. in *Proceedings of the 38th international conference on Software Engineering*. ICSE '16, ACM Press, Austin, TX, USA, pp. 655-666. <https://doi.org/10.1145/2884781.2884821>

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# Featured Model-based Mutation Analysis

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## ABSTRACT

Model-based mutation analysis is a powerful but expensive testing technique. We tackle its high computation cost by proposing an optimization technique that drastically speeds up the mutant execution process. Central to this approach is the Featured Mutant Model, a modelling framework for mutation analysis inspired by the software product line paradigm. It uses behavioural variability models, viz., Featured Transition Systems, which enable the optimized generation, configuration and execution of mutants. We provide results, based on models with thousands of transitions, suggesting that our technique is fast and scalable. We found that it outperforms previous approaches by several orders of magnitude and that it makes higher-order mutation practically applicable.

## Keywords

Mutation Analysis, Variability, Featured Transition Systems

## CCS Concepts

•Software and its engineering → Software testing and debugging; Software product lines; •General and reference → Performance;

## 1. INTRODUCTION

Mutation analysis is an established technique for either evaluating test suites' effectiveness [5, 24, 50] or supporting test generation [23, 50, 54]. It works by injecting artificial defects, called *mutations*, into the code or the model under test, yielding *mutants*, and measures test effectiveness based on the number of detected mutants.

Researchers have provided evidence that detecting mutants results in finding real faults [5, 33] and that tests designed to detect mutants reveal more faults than other test-

ing criteria [7, 50]. This has been shown to be the case for model-based mutation too: Aichernig *et al.* [1] report that model mutants lead to tests that are able to reveal implementation faults that were neither found by manual tests, nor by the actual operation, of an industrial system. In addition, model-based mutation's premise is to identify defects related to missing functionality and misinterpreted specifications [13]. This is desirable since code-based testing fails to identify these kinds of defects [28, 62].

Despite its power, mutation analysis is expensive, due to the large number of mutants that need to be generated and assessed with the candidate test cases. While this problem has been researched for code-based mutation, e.g., [32, 55], it remains open in the model-based context. Since typical real-world models involve thousands of mutants and test suites involve thousands of test cases, millions of test executions are needed. Addressing this problem is therefore vital for the scalability of mutation. This is a known issue that requires further research, as pointed out in the surveys of Jia and Harman [31], and Offutt [50].

To address this problem, we take inspiration from past research on software product lines (SPL). As suggested in our vision paper [18], we propose an approach to model mutants as *members* (also called *variants* or *products*) of an SPL. Considering mutants as part of a family rather than in isolation yields a considerable advantage: shared execution at the model level [15]. This contrasts with existing SPL approaches [36, 37, 48] which require code and hence do not apply to model mutants.

The key idea of our approach is to encode the mutants as products of an SPL. To do so, we use a Feature Diagram (FD) [34] together with a Featured Transition System (FTS) that represent the variations (i.e., applications of mutation operators) and the behaviour of the mutants, respectively. FTSs have been proposed by Classen *et al.* [15] to compactly model the behaviour of an SPL. They consist of a Transition System (TS) where each transition has been tagged to indicate which products are able to execute the transition. We use FTS to embed all the mutants in one model, called the *Featured Mutants Model* (FMM).

To optimise test execution, we rely on the FMM to: (i) only execute tests with mutants that are reachable by the tests, (ii) share common transitions among multiple executions and, (iii) merge different executions that reach previously visited states. Therefore, instead of performing multiple runs, i.e., executing a test against each mutant, we perform a single execution of the FMM.

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ICSE '16, May 14-22, 2016, Austin, TX, USA

© 2016 ACM. ISBN 978-1-4503-3900-1/16/05...\$15.00

DOI: <http://dx.doi.org/10.1145/2884781.2884821>

We performed an empirical evaluation which demonstrated that FMM: (i) yield significant execution speedups, i.e., from 2.5 to 1,000 times faster compared to previous approaches; (ii) make mutation analysis applicable to models much larger than those used in previous studies; and (iii) make higher-order mutation feasible.

In summary, the contributions of this paper are:

- FMM, a compact model which allows to easily generate and configure mutants (of any order) of a transition system.
- An implementation of FMM in the Variability Intensive Behavioural teSting (ViBES) framework [19] making it the first mutation testing tool for behavioural models that supports higher-order mutation. Our implementation is publicly available at: <https://projects.info.unamur.be/vibes/>.
- A shared execution technique that allows executing tests with all relevant mutants in a single run. To the authors’ knowledge, this is the first approach that optimizes model-based mutation analysis.
- An empirical evaluation on a mix of real-world and generated models.
- Empirical results that contradict the general belief that “higher order mutation testing is too computationally expensive to be practical” [30]. Instead, they suggest that it can be applied to real-world systems.

The rest of this paper is organised as follows: Section 2 recalls the main concepts of mutation testing and variability modelling; Sections 3 and 4 present our approach and results, respectively. Finally, Section 5 discusses related work and Section 6 concludes the paper.

## 2. BACKGROUND

### 2.1 Transition Systems

In this paper, we consider transition systems as a fundamental formalism to express system behaviour. Our definition is adapted from [6], where atomic propositions have been omitted (we do not consider state internals):

**DEFINITION 1** (TRANSITION SYSTEM (TS)). *A TS is a tuple  $(S, Act, trans, i)$  where  $S$  is a set of states,  $Act$  is a set of actions,  $trans \subseteq S \times Act \times S$  is a transition relation such that the TS is deterministic (with  $(s_1, \alpha, s_2) \in trans$  sometimes denoted  $s_1 \xrightarrow{\alpha} s_2$ ), and  $i \in S$  is the initial state.*

As a convention, we start and end executions in the initial state. This ensure that they are finite. Fig. 1(a) presents a (simple) example TS of a payment operation on a *Card Payment Terminal* (CPT). The model starts in the initial (*Init*) state where the card holder has to insert his card. The CPT will select a means of payment (e.g., Visa, Mastercard, American Express, etc.) and negotiate with the card chip to agree on a protocol for the transaction. Transactions can be either performed on-line or off-line using a PIN code or a signature. Once the card holder has been identified, the CPT will perform the transaction off-line or on-line (and in this case, it will contact the card issuer to authorize the transaction) and update the information on the card chip.

**Table 1: Summary of model-based mutation approaches for behavioural model.**

Reference	Year	Employed Models	Av. tool	HOM
Fabbri <i>et al.</i> [22]	1999	statechart	-	-
Offutt <i>et al.</i> [49]	2003	statechart	-	-
Belli <i>et al.</i> [9]	2006	finite state automata & statechart	-	-
Belli <i>et al.</i> [8]	2011	finite state automata & statechart	-	✓
Aichernig <i>et al.</i> [1]	2014	State Machines	✓	-
Aichernig <i>et al.</i> [2]	2014	State Machines	-	-
Lackner & Schmidt [40]	2014	State Machines	-	-
Aichernig <i>et al.</i> [3]	2015	State Machines	-	-
Krenn <i>et al.</i> [39]	2015	State Machines	✓	-
This paper	2016	Transition Systems	✓	✓

Once the transaction has been completed (or aborted), the card holder may remove her card from the CPT.

In model-based testing [61], test cases are derived from such a model of the system. For instance, a test case is  $atc = (insert\_card, select\_app, negotiate\_with\_card, abort, remove\_card)$  for the TS of Fig. 1(a). Test selection can be guided by coverage criteria. For instance, the all-actions coverage criterion specifies that all the actions of the considered TS must appear in at least one of the selected abstract test cases. In this paper, we do not consider test concretization (see e.g. [44]).

### 2.2 Mutation Testing

In model-based testing, mutants are introduced based on model transformation rules that alter the system specification. These rules are called *mutation operators*. An example of mutant obtained from the *state missing operator* applied on the *Go\_offline* state of the CPT system, is presented in Fig. 1. There are two kinds of mutants, *first-order* mutants when the original and the mutant models differ by a single model transformation, and *higher-order* mutants, derived from the original model after multiple transformations.

When a mutant is detected by a test case, it is called *killed*. In the opposite situation, it is called *live*. In our case, a mutant is killed if a test case cannot be executed. For instance, the test case  $tc = (insert\_card, select\_app, negotiate\_with\_card, check\_PIN\_online, go\_offline, update\_card\_info, remove\_card)$  will kill the mutant of Fig. 1(b) since it fails to execute completely. A test case that can be completely executed on a mutant will not detect (kill) it, e.g., the test case  $atc$  defined in Section 2.1 will leave the mutant of Fig. 1(b) live because it can be executed completely.

To measure the adequacy of testing, a standard metric called *mutation score* is used. It is defined as the ratio of mutants killed by the test set under assessment to the total number of considered mutants. To calculate the mutation score, one has to execute the whole test set against every selected mutant. In our case, we consider deterministic TS and stop the execution of a test case as soon as the TS is unable to fire the next action. For the test case  $tc$  on the mutant in Fig. 1(b), the execution is stopped when it reaches

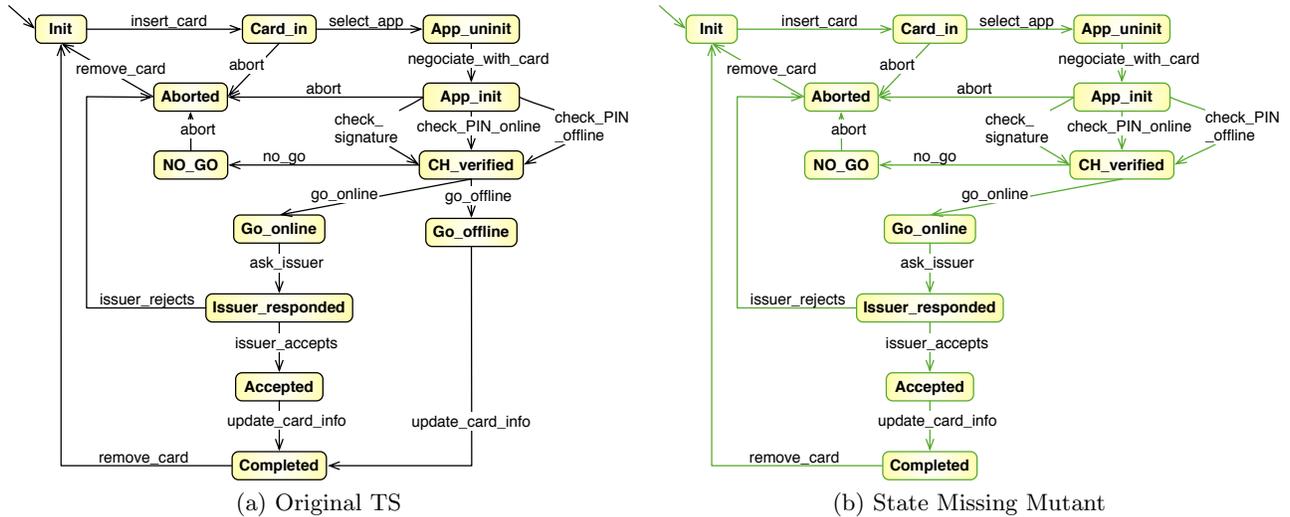


Figure 1: Card Payment Terminal: the original system and a mutant (state *Go\_offline*)

the *CH\_Verified* state as it may not execute the next action (*go\_offline*) in *tc* and the mutant TS is considered killed by *tc*. The mutant would have been kept live if another test case *tc'* had followed the “online path” after *CH\_Verified*. Mutant execution is a time-consuming task [31], especially for large models. In our experiments, it took 3 days to run the mutants of our model with 10,000 states against each test case. The times reported in Table 6 are for running one mutant against one test case. In the following, we will call this approach of executing each test against each mutant model separately, the *enumerative approach*.

Related studies on model-based mutation approaches for behavioural model are briefly described in Table 1: publication, year of publication, model types used, available tool and the use of Higher-Order Mutation (HOM). In literature, most of the existing approaches have been evaluated based on small models using a brute force technique that executes all mutants with all tests. This results in extremely long execution times and hinders scalability (in space and/or execution time). We believe that tool scalability, and the lack of available tools, are the main reasons why there are few model-based testing studies and they mostly use small models. In their recent survey, Jia and Harman [31] motivate the need for additional research on using mutation on program artefacts other than code. We believe that, since our tool is publicly available and scales well, it will foster experimentation on model-based mutation.

### 2.3 Variability Modelling

SPL engineering is a sub-discipline of software engineering based on the idea that we can build products (aka members) of the same family by systematically reusing software assets. Some assets are common to all members, whereas others are only shared by a subset of the family. Such variability is commonly captured by the notion of *feature*, defined as a unit of difference between products. Individual features can be specified using languages such as UML, and their relationships by Feature Diagrams (FDs) [34]. An ex-

ample of FD is provided at the top of Fig. 2. In this figure, the root feature (*m*) has 3 sub-features (*smi*, *aex*, *wis*) connected using a *xor* operator. FDs have their semantics defined in terms of *valid products*, i.e., legal combinations of features. In the FD of Fig. 2, a valid product is  $\{m, smi, smi\_Go\_offline\}$  while the product  $\{m, smi, smi\_Go\_offline, aex, aex\_issuer\_accepts\}$  is invalid because it does not respect the *xor* constraints. FD semantics is formal [58] and FDs can be encoded as boolean constraints. Thus, SAT or BDD solvers are commonly used to enumerate products or to check their validity.

The main challenge in SPL engineering is to deal with the combinatorial explosion induced by the number of possible products ( $2^N$  for  $N$  features in the worst case). FTSS address this problem and enable the efficient behavioural model checking of SPLs [15]. FTSS are Transition Systems (TSs) where each transition is labelled with a feature expression specifying which products of the SPL can execute the transition. A FTS is thus a compact representation of the behaviour of an SPL:

**DEFINITION 2** (FEATURED TRANSITION SYSTEM [15]). *A Featured Transition System (FTS) is a tuple  $(S, Act, trans, init, d, \gamma)$ , where:  $S, Act, trans$  are defined according to definition 1;  $d$  is an FD;  $\gamma : trans \mapsto \llbracket d \rrbracket \mapsto \{true, false\}$  is a labelling function specifying for each transition which valid products may execute it; this function is represented as a boolean expression over the features of  $d$ ; and  $init : S \mapsto (\llbracket d \rrbracket \mapsto \{true, false\})$  a total function that indicates if a state  $i \in S$  is an initial state for a product  $p \in \llbracket d \rrbracket$ , such that for every product  $p \in \llbracket d \rrbracket$  there is exactly one initial state, which allows one to model mutants that change the initial state of the system.*

A FTS example is provided at the bottom of Fig. 2. Transition

$$CH\_verified \xrightarrow{go\_offline / \neg smi\_Go\_offline} Go\_offline$$

may only be executed in products with a valid configuration where the *smi\_Go\_offline* feature is not selected.

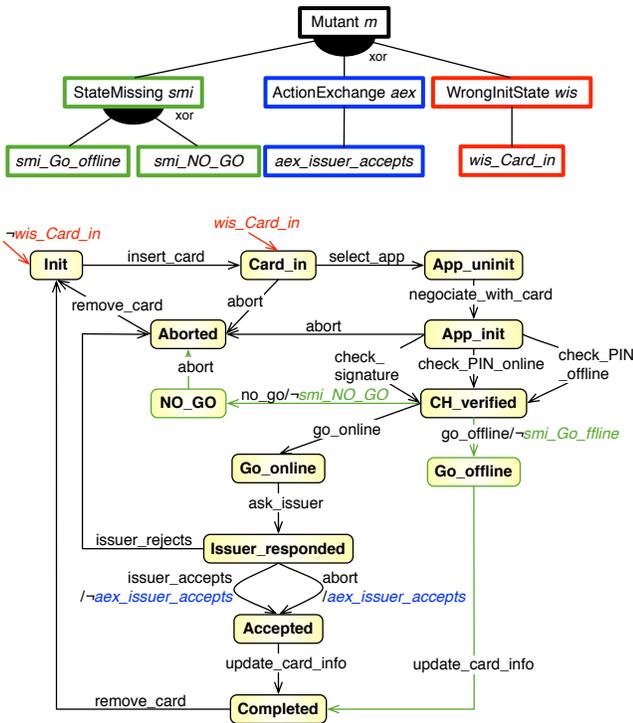


Figure 2: Featured Mutant Model of Card Payment Terminal

### 3. COMPACT MUTANTS MODEL

The key idea behind our approach is to represent mutants as a family of variations of the System Under Test (SUT). We model the SUT’s behaviour using a TS, called the original TS (to distinguish it from the mutant TS). It is possible to model these variants as an FTS and its corresponding FD, where each feature corresponds to one application of one mutant operator on the original TS. The FTS and the FD represents all the possible mutants of an original TS and is called the *Featured Mutants Model* (FMM).

For example, the FMM of Fig. 2 has an FD (at the top) with 3 mutation operators: the state missing (SMI) operator, which produces a mutant where one state is missing; the action exchange (AEX) operator, which produces a mutant where one transition has its action changed (to another action); and the wrong initial state (WIS) operator, which produces a mutant where the initial state has been set to another state. In this instance of the FD, the SMI operator has been applied twice (*smi\_go\_offline*, *smi\_NO\_GO*), and the AEX and WIS operators have been applied one time each (*aex\_issuer\_accepts*, *wis\_Card\_in*). This FD represents four mutants, where at most one leaf feature is selected. The FTS at the bottom of Fig. 2 represents all the possible variations, corresponding to the four mutation operators, of the original TS.

In order to derive one particular mutant (TS) from the FMM, one may use the FTS *projection operator* [15]. Practically, this operator will first need a valid product representing the desired mutant, e.g.,  $p = \{m, smi, smi\_Go\_offline\}$ ; then, each feature expression of the FTS is evaluated with features belonging to the product replaced by true, and other features replaced by false; finally, transitions with a feature

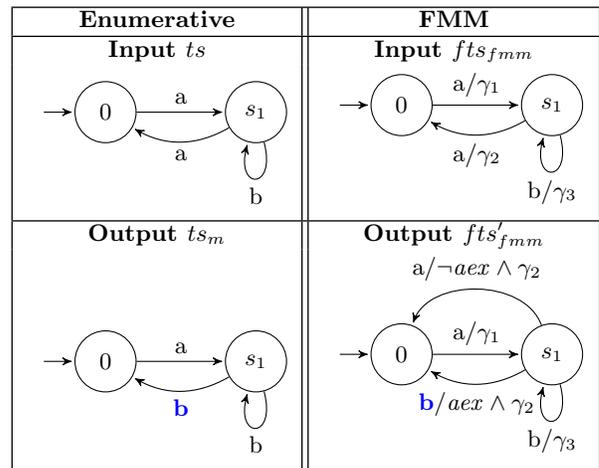


Figure 3: An example of mutation, the AEX operator

expression evaluated to false (i.e., where  $\gamma p = false$ ) are removed from the FTS, and the initial state is set to the only state such that the feature expression on the initial transition is true (i.e., where  $init(i, p) = true$ ). For instance, the projection of the FMM of Fig. 2 on  $p$  will produce the mutant TS of Fig. 1(b).

#### 3.1 Building the Featured Mutants Model

We rely on the state-of-the-art operators proposed by Fabri *et al.* [22] to generate mutants from a TS:

- SMI State Missing operator removes a state (other than the initial state) and all its incoming/outgoing transitions;
- WIS Wrong Initial State operator changes the initial state;
- AEX Action Exchange operator replaces the action linked to a given transition by another action;
- AMI Action Missing operator removes an action from a transition;
- TMI Transition Missing operator removes a transition;
- TAD Transition Add operator adds a transition between two states;
- TDE Transition Destination Exchange operator modifies the destination of a transition.

Each operator can be used to generate mutants using the enumerative approach, where each mutant is formed as a new variation of the original TS (possibly introducing non determinism with AEX and TAD operators), or using the FMM approach, where each mutant is an addition to the FD. We detail hereafter the mutant generation procedures.

**Enumerative approach:** In the enumerative approach, each operator ( $op$ ) is defined as a model transformation with input a TS ( $ts$ ) representing the behaviour of the SUT. It produces another (mutant) TS ( $ts_m$ ) representing the result of an operator on  $ts$ . For instance, AEX operator, shown on the left of Fig. 3, replaces the action  $a$  on transition  $s_1 \xrightarrow{a} s_0$  by  $b$ . Algorithm 1 details the enumerative approach where the set of mutants ( $mut_s$ ) is produced by applying each operator (in  $Ops$ ) with random parameters a number of times (defined for each operator by the *times* function) on the original TS (line 4).

---

**Algorithm 1** Mutant generation, enumerative approach

---

**Require:**  $ts = (S, Act, trans, i)$  {original TS}  
 $Ops$  {the set of operators to use}  
 $times : Op \rightarrow \mathbb{N}$  {function specifying for each operator the number of applications}  
**Ensure:**  $return = muts$  {set of produced mutants}  
1:  $muts \leftarrow \emptyset$   
2: **for all**  $op \in Ops$  **do**  
3:   **for all**  $i$  **between** 1 **and**  $times(op)$  **do**  
4:      $muts \leftarrow muts \cup op(random(ts))$   
5:   **end for**  
6: **end for**  
7: **return**  $muts$

---

---

**Algorithm 2** Mutant generation, FMM approach

---

**Require:**  $ts = (S, Act, trans, i)$  {original TS}  
 $Ops_{fmm}$  {set of operators to use}  
 $times : Op_{fmm} \rightarrow \mathbb{N}$  {function specifying for each operator the number of applications}  
**Ensure:**  $fmm = (fts_{fmm}, fd_{fmm})$  {FMM representing the mutants}  
1:  $\gamma \leftarrow (\lambda t \rightarrow true)$   
2:  $fts_{fmm} \leftarrow (S, Act, trans, i, fd_{fmm}, \gamma)$   
3:  $fd_{fmm} \leftarrow (m)$  {initialised to root feature  $m$ }  
4: **for all**  $op_{fmm} \in Ops$  **do**  
5:   **for all**  $i$  **between** 1 **and**  $times(op)$  **do**  
6:      $fmm \leftarrow op_{fmm}(fmm)$   
7:   **end for**  
8: **end for**  
9: **return**  $fmm$

---

**FMM approach:** In the FMM approach, an operator ( $Op_{fmm}$ ) is defined as a model transformation of a FMM (representing existing mutants), that produces a FMM representing (the previously existing mutants and) the result of the  $Op_{fmm}$  mutation *on the original TS* (obtained in the FMM's FTS by replacing the features by false in the feature expressions). For instance, on the right of Fig. 3, the  $AEX_{fmm}$  operator replaces the action  $a$  on transition  $s_1 \xrightarrow{a} s_0$  of the base model by  $b$  as follows:

1. adding the feature expression  $\neg aex$  on transition  $s_1 \xrightarrow{a/\gamma_2} s_0$ , stating that  $s_1 \xrightarrow{a/\neg aex \wedge \gamma_2} s_0$  may be fired only if the  $aex$  mutation is inactive (and if  $\gamma_2$  is true);
2. adding a transition  $s_1 \xrightarrow{b/aex \wedge \gamma_2} s_0$ , stating that the transition is fired with a  $b$  action only if the  $aex$  mutation is active (and if  $\gamma_2$  is true);
3. adding an  $aex$  feature to  $fd_{fmm}$  representing the mutation done by  $Op_{fmm}$  (not shown in Fig. 3).

Algorithm 2 details the automated FMM building approach. We start with the original TS (line 2) and a  $\gamma$  function that labels each transition with a true feature expression (line 1). We then apply mutation operators ( $Ops_{fmm}$ ) a specified number of times ( $times(op)$  line 5). Contrary to the enumerative approach, the mutation operators are applied on the FMM under construction, which is reused in the next iteration (line 6). This is mandatory as the FMM contains all the previous mutations that are taken into account in the model transformations (e.g., the  $\gamma_i$  expressions in Fig. 3). As we choose to only perform  $Op_{fmm}$  mutations on the original

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**Algorithm 3** FMM mutant execution

---

**Require:**  $fmm = (fts_{fmm}, fd_{fmm})$  {FMM model}  
 $tc = (\alpha_1, \dots, \alpha_n)$  {test case defined over the original TS}  
**Ensure:**  $live$  {feature expression representing the mutants live after executing  $tc$ }  
1:  $live \leftarrow false$   
2:  $paths \leftarrow \{(i \xrightarrow{\alpha_1/\gamma_1} \dots \xrightarrow{\alpha_n/\gamma_n} i)\}$  {paths in  $fts_{fmm}$ }  
3: **for all**  $p \in paths$  **do**  
4:    $live \leftarrow live \vee (\bigwedge_{\gamma_i \in p} \gamma_i)$   
5: **end for**  
6: **return**  $live$

---

TS, this forbids operator composition on (previously) mutated elements. Doing so ensures that first-order mutation maps to only one edit of the original TS. Further details about the operators and specificities of the transformations can be found on the VIBeS website [17] in a technical note.

### 3.2 Featured Mutants Model Execution

In our context, test cases are defined as a sequence of actions in a TS ( $ts$ ), such that one execution form a path starting from and ending at the initial state ( $i$ ) [20]:  $tc = (\alpha_1, \dots, \alpha_n)$  such that  $\exists(i \xrightarrow{\alpha_1} s_k, \dots, s_l \xrightarrow{\alpha_n} i)$ . Recall that in the enumerative approach, if a test case cannot be executed by the mutant (denoted  $m \not\stackrel{tc}{\Rightarrow}$ ) or does not end in the initial state (considered as the accepting state), it is considered killed. Otherwise, the mutant is considered live. The set of live mutants, according to  $tc$  and the mutant set  $muts$ , is defined as:

$$liveEnum(muts, tc) = \{m \in muts \mid m \stackrel{tc}{\Rightarrow}\}$$

In the FMM approach, a test case can be executed on an FMM's ( $fmm$ ) FTS (noted  $fts_{fmm} \stackrel{tc}{\Rightarrow}$ ), if there exists at least one mutant able to execute it. The enumerative approach executes each test case on each mutant separately. In contrast, one execution of a test case on the FMM explores all the reachable mutants (identified by the collected feature expression  $\gamma$ ). The set of live mutants in the FMM approach is defined as:

$$liveFMM(fmm, tc) = \{p \in \llbracket fd_{fmm} \rrbracket \mid fts_{fmm}^p \stackrel{tc}{\Rightarrow}\}$$

Concretely, all possible paths in  $fts_{fmm}$  starting from  $i$  and ending in  $i$  will be considered, which allows to deal with possible non-determinism introduced by a mutation. The live mutants are those able to execute at least one of those paths, i.e., those for which the product  $p$  satisfies all the feature expressions on the transitions of the considered path. For instance, the test case:

```
tc = (insert_card, select_app, negotiate_with_card,
      check_PIN_offline, go_offline, update_card_info,
      remove_card)
```

Executing the FMM of Fig. 2, it will fire the following transitions:

$$\begin{aligned}
& (\xrightarrow{\neg wis\_Card\_in} Init, Init \xrightarrow{insert\_card} Card\_in, \\
& \quad Card\_in \xrightarrow{select\_app} App\_uninit, \\
& \quad App\_uninit \xrightarrow{negociate\_with\_card} App\_init, \\
& \quad App\_init \xrightarrow{check\_PIN\_offline} CH\_verified, \\
& \quad CH\_verified \xrightarrow{go\_offline/\neg smi\_go\_offline} Go\_offline, \\
& \quad Go\_offline \xrightarrow{update\_card\_info} Completed, \\
& \quad Completed \xrightarrow{remove\_card} Init)
\end{aligned}$$

These transitions may only be fired by mutants for which all the features expressions are *true*. In such a case, mutants need to respect the following constraint:

$$\neg wis\_Card\_in \wedge \neg smi\_go\_offline$$

All mutants in the FD of Fig. 2 that satisfy this feature expression remain live after the execution of *tc*. The set of mutants killed by the test case is computed using the conjunction of  $fd_{fmm}$  and the negation of this feature expression:  $fd_{fmm} \wedge (wis\_Card\_in \vee smi\_go\_offline)$ , which corresponds to the set of mutants:

$$\{(m, wis, wis\_Card\_in), (m, smi, smi\_go\_offline)\}$$

In practice,  $liveFMM(fmm, tc)$  will produce a feature expression representing all the live mutants as detailed in Algorithm 3. Initially, the algorithm computes all the paths in  $fts_{fmm}$  corresponding to the sequence of actions in *tc* (line 2). For one path, the conjunction of the feature expressions gives the mutants able to execute this path (line 4). Effort is saved this way by ignoring unreachable mutants and by sharing the execution of the common transitions. This conjunction disjuncts with the conjunctions of the others paths to get the feature expression representing all the live mutants (line 4). This step results in savings due to merging of the considered executions. For performance reasons, the *paths* variable uses a tree representation to merge common prefixes of different paths.

We implemented the different mutant operators described in Section 3.1 in order to perform classical mutation testing (enumerative approach) as well as FMM generation and execution in VIBeS, our *Variability Intensive Behavioural teSting* Java framework [17].

### 3.3 FMMs as Higher-Order Mutants Model

Higher-order mutants can be valuable since some of them tend to be hard to kill [25]. However, the number of mutants grows exponentially according to the order *n* and explode the involved cost. This is obvious in Algorithm 1, for the enumerative approach, which generates all the *n* - 1 mutants to generate the *n*-order ones.

Using the FMM approach, modelling higher-order mutation comes at (nearly) no cost. In a FMM ( $fts_{fmm}, fd_{fmm}$ ), the set of allowed mutants (i.e., variations in  $fts_{fmm}$ ) is represented by the feature diagram ( $fd_{fmm}$ ). For instance, the constraints in the  $fd_{fmm}$  of Fig. 2 allows to have exactly one mutant at a time. Meaning that all valid mutants (products) of this FMM will have at most one variation from the original TS made by a mutation operator, e.g., Fig. 1(b) has

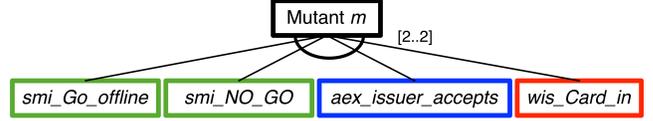


Figure 4: The Order 2 FMM of the CPT Example

(only) *smi\_go\_offline* feature active. The *n* order mutants are represented by modifying the constraints on the  $fd_{fmm}$  so that they have exactly *n* mutations at a time. It means that generating the FMM using Algorithm 2 will also generate the FTS (which will be the same) for order 1 to *n* FMMs. For instance, the card payment terminal has the same FTS, for all orders as shown in Fig. 2, but differ on the FD that is described by Fig. 4 by the group cardinality stating that exactly 2 subfeatures have to be selected. The FMM will compactly represent all the  $C_2^4 = 6$  2-order mutants.

**All-order mutants:** Using the same argument, we generalize to higher-order mutants. In this case, the FMM represents a single model with all possible *n* orders of mutants (with *n* between 1 and the number of possible mutants which is the number of leaf features in the FMM's FD). By setting the group cardinalities of the FD in Fig. 4 to  $[1..*]$ . A valid product (mutant) of the FD will contain at least one applications of mutation operator, e.g., a product  $p = \{m, smi\_go\_offline\}$ , but also  $p' = \{m, smi\_go\_offline, smi\_NO\_GO\}$ , or  $p'' = \{m, smi\_go\_offline, wis\_Card\_in\}$ , etc. In this case, the FMM compactly represent all the  $\sum_{k=1}^4 C_k^4 = 15$  *n*-order mutants. The number of live mutants after the execution of a test case (*tc*) on a FMM (*fmm*) can be obtained by counting the number of SAT solutions (i.e., the number of possible assignments for each feature) to  $fd_{fmm} \wedge liveFMM(fmm, tc)$ . Where  $fd_{fmm}$  is the FMM's FD encoded as a boolean formula, i.e., the disjunction of the mutation operator (*Ops*):  $fd_{fmm} = \bigvee_{o \in Ops} o$ . For a test set (*ts*), the number of live mutants is computed by counting the number of SAT solutions to

$$\left( \bigvee_{o \in Ops} o \right) \wedge \left( \bigwedge_{tc \in ts} liveFMM(fmm, tc) \right).$$

## 4. EVALUATION

We formulate our research questions as follows:

- RQ1 *How does the FMM scheme compare with the “enumerative approach” in terms of execution time ?*
- RQ2 *Is higher-order mutation under the FMM scheme tractable?*

### 4.1 Setup

We compare two test execution approaches: the *enumerative approach*, which is the classical mutation testing approach used by previous research [2] where each test case is executed against each mutant, and the *FMM approach*, where each test case is executed (only once) on the FMM.

**Models:** We consider models from different sources with varying size. Table 2 details the employed models. For each model, we measure: the number of states (*States*); the number of transitions (*Trans.*); the number of actions (*Act.*); the average degree of the different states that correspond to the average number of incoming or outgoing transitions per

**Table 2: Models characteristics**

Model	States	Trans.	Act.	Avg. deg.	BFS height	Back lvl tr.
S. V. Mach.	9	13	14	1.44	5	3
Minepump	25	41	23	4.64	15	9
Claroline	106	2055	106	19.37	1	105
AGE-RR	772	6,639	772	8.60	328	408
Elsa-RR	384	1,214	384	3.16	194	174
Elsa-RRN	615	1,771	615	2.88	369	289
Random	10,000	13,652	120	1.37	7,924	3,303

state (*Avg. deg.*); the maximal number of states between the initial state and another state when traversing the TS in breadth-first search (*BFS height*); the number of transitions starting from a state and ending in another state with a lower level when traversing the TS in breadth-first search (*Back lvl tr.*).

Our models are: the soda vending machine model (*S. V. Mach.*) which is a small example modelling the behaviour of a machine selling soda and tea [14]; the mine pump (*Minepump*) that models the behaviour of a pump which has to keep a mine safe from flooding by pumping water from a sink while avoiding methane explosions [14]; the Claroline website (*Claroline*) that represents the navigational usages of the online course management platform used at the University of Namur (<http://webcampus.fundp.ac.be>). It has been reverse-engineered from an Apache log using a 2-gram inference method [19,59]; the WordPress models (*AGE-RR*, *Elsa-RR*, and *Elsa-RRN*) that represent the navigational usage of two different WordPress instances. They are also reverse-engineered using a 2-gram inference method. For the *AGE-RR* and *Elsa-RR*, we considered only the request type (e.g., POST, GET, HEAD) and the requested resource (e.g., "/index.php") in the sequences used. For the *Elsa-RRN* model, we considered the request type, the requested resource and the parameter names (e.g., "?page=") in the sequences used as input of the 2-gram inference method [59]. The random model has been generated based on the following procedure: *a*) we generate a set of random graphs (basically directed arcs and nodes) and compute the different measures from Table 2 (except number of actions) on them; *b*) we selected those graphs that are likely to represent a real system according to Pelánek [56], i.e., those having a small average degree, a large BFS height and a small number of back level edges (in this order); *c*) we applied a random labelling multiple times and computed the occurrence probability, i.e., the probability of the labels to obtain a set of randomly generated TSs; *d*) we selected the TS that had the following properties<sup>1</sup>: the probability of the most occurring label in the TS was less than or equal to 6%, and the cumulated probability of the 5 most frequently occurring labels was less than or equal to 20% [57]; *e*) we ended up with one random model as recorded in Table 2.

**Test Cases:** For every model, we generate one set of tests using random walks on the TS and one set satisfying the all-actions criterion. The test sets were then executed with the enumerative and the FMM processes. Table 3 records the average size (and standard deviation) of the randomly generated test cases, the size of the generated all-actions coverage-driven test set and the average size (and standard

**Table 3: Test sets characteristics**

Model	Rand. test set		All act. test set		
	Avg. size	Std. dev.	Nb. t.c.	Avg. size	Std. dev.
S. V. Mach.	4.78	1.34	3	5.33	2.08
Minepump	5.65	1.23	9	6.11	1.45
Claroline	17.11	16.97	11	13.18	9.20
AGE-RR	21.13	24.58	274	27.11	33.62
Elsa-RR	10.57	13.12	109	21.10	33.45
Elsa-RRN	10.45	14.05	148	23.20	43.49
Random	469.62	279.34	2	468.50	118.09

**Table 4: Mutant operators**

Model	WIS	TMI	AEX	TDE	TAD	AMI	SMI	Total
S. V. Mach.	1	1	1	1	1	1	1	7
Minepump	2	4	4	4	4	3	2	23
Claroline	9	188	205	204	205	189	9	1,009
AGE-RR	73	525	663	663	663	516	75	3,178
Elsa-RR	36	102	121	121	121	106	38	645
Elsa-RRN	57	153	177	177	177	155	57	953
Random	942	1,276	1,365	1,365	1,365	1,295	954	8,562

deviation) of its test cases. The size of the random test set is arbitrarily fixed to 100 test cases.

**Model Mutants:** We used the operators presented in Section 3.1. Operators modifying states (*WIS* and *SMI*) or transitions (*TMI*, *AEX*, *TDE*, *TAD*, and *AMI*), resp., were applied arbitrarily for 1/10 of the number of states or transitions, resp., in the model (with 1 as bottom value). Since the operands are randomly chosen, we forbid multiple applications of any operator on the same operands to avoid duplicated mutants [52]. Table 4 presents the number of mutants generated per operator for the studied models.

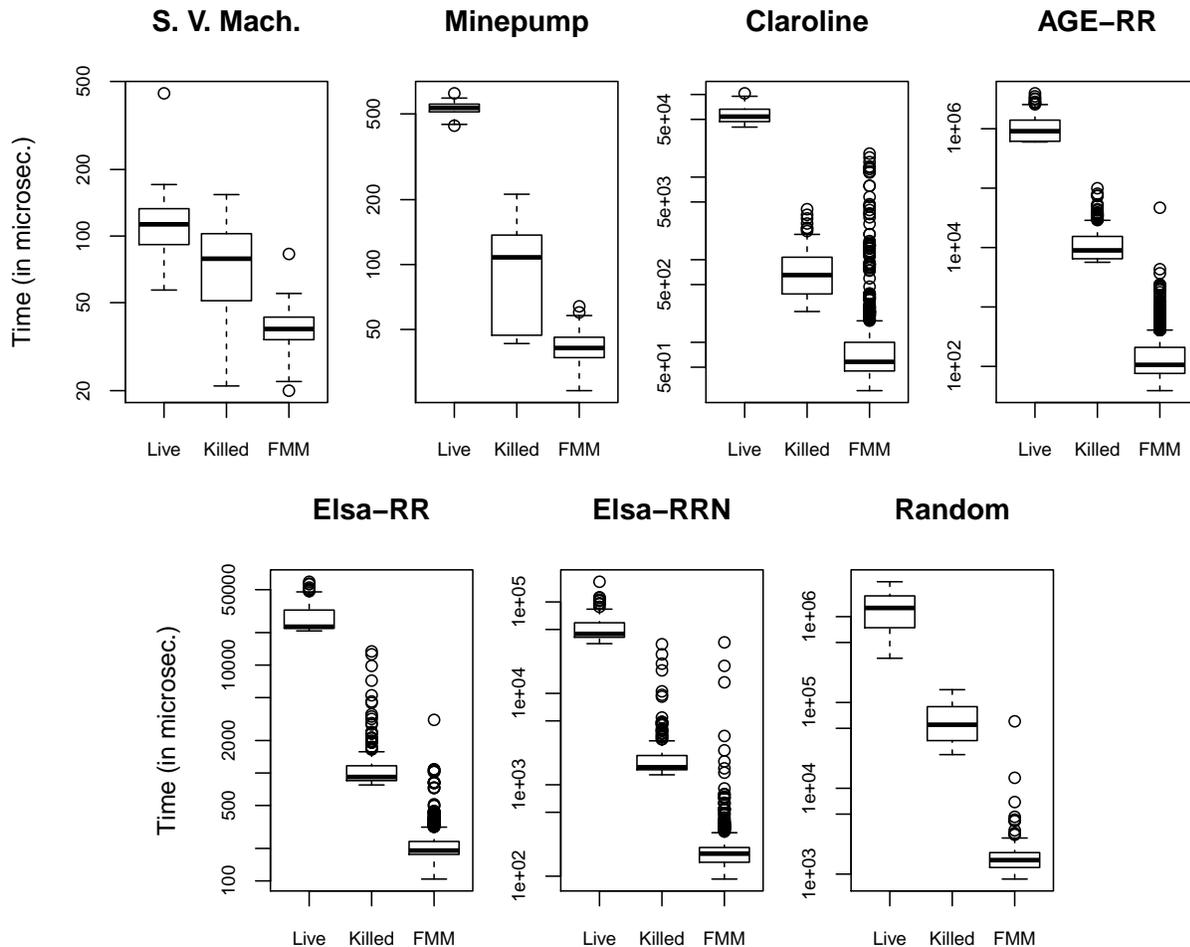
**Mutant Execution:** To avoid execution time bias from the underlying machines, we execute each test case 3 times with each considered mutant (for the *enumerative version*) and on the FMM (for the *family version*).

Experimentation was performed on an Ubuntu 14.04 LTS Linux (kernel 3.13) machine with Intel Core i3 (3.10GHz) processor and 4GB of memory. The complete experiment took approximately 2 weeks.

## 4.2 Results and Discussion

Fig. 5 presents the distribution of the test execution time (in logarithmic scale on the *y* axis) for each studied model with a box plot. The first two columns represent the total execution time taken by each test case when executed on the live mutants and on the killed mutants according to the enumerative approach. The third box presents the execution time of the FMM (FMM approach). Note that while the killed mutants do not require a complete execution in the enumerative approach, it is required for the FMM mutants. This might provide an advantage to the enumerative approach. To assess this, we consider the killed and the live mutants separately. In all cases, we measure only the execution of the models, avoiding time bias due to I/O operations. As the execution time of a test case partially depends on its size, the high number of outliers in Fig. 5 is explained by the variation of the test cases sizes. Tables 5 and 6 record different statistics over the execution time of the models in  $\mu$ -seconds. For the enumerative approach, executing a test case on mutants that will remain live takes more time than executing the same test cases on mutants that are killed. This was expected since killed mutants do

<sup>1</sup>These properties are likely to represent real systems [56]



**Figure 5: Execution Time:** time required by a test case to execute with live, killed mutants and the FMM mutants, time is measured in  $\mu sec.$ .

not require a complete execution of the test case. In both cases, the FMM execution runs faster, i.e., running a test case on all the mutants at once is very fast, despite the more complex (needed) exploration of the FMM’s FTS.

Regarding **RQ1**, the box plots of Fig. 5 and the values of Tables 5 and 6 confirm that the execution time required by the FMM approach is considerably lower than the time required by the enumerative approach. The difference escalates to several orders of magnitude when considering live mutants. The difference between family-based and enumerative approaches increases with the size of the model, indicating the improved scalability of our approach.

To evaluate the statistical significance, we use a Wilcoxon rank-sum test for the different models we considered: we obtain a  $p$ -value of  $1.343e - 09$  for the random model and  $p$ -values smaller than  $2.2e - 16$  for the other models, confirming the hypothesis that FMM significantly outperforms the enumerative approach, when considering 0.001 significance level.

#### 4.2.1 All-Order Mutation

Table 7 presents the number of all-order mutants for our models, the number of mutants live after executing the random and all-actions test sets (computed using SAT4J 2.3.5),

and their mutation score. *Mem. Overflow* denotes an overflow during SAT solving, improving this step by, for instance, reducing the boolean formula to process is part of our future work. Columns 5 and 8 give the SAT-solving computation time (we set a timeout of 12 hours).

Overall, our results suggest that higher-order mutation under the FMM scheme is tractable, answering positively to **RQ2**. In particular, all-order mutation achieves very good mutation scores ( $MS \geq 0.99$ ) when compared to first-order mutation when this score can be computed. In our future work, we intend to: (i) improve the scalability of mutation score computation; and (ii) assess the practical relevance of higher-order in test sets comparison.

Only one mutant is live for the soda vending machine and the mine pump models. This mutant is a first order mutant resulting from the TAD operator. Indeed, the TAD operator adds new transition which cannot be detected by test cases solely generated from the original TS, since this transition does not exist in this model. All-order mutation enables to quickly kill mutants of any order and to focus on the interesting ones from a selective mutation perspective. For example, the 2916 remaining live mutants resulting from the execution of the all-action test suite are relevant to study the mutation operators involved. Of course, they can also be

**Table 5: Mutant (1st order) execution time in  $\mu$ -seconds: minimal, maximal, median, mean, standard deviation for every test case on all live and killed mutants of the enumerative method and of the FMM. Mutation score (MS) of the all actions and random test sets are provided for each model.**

S. V. Mach. model (all act. MS: 0.85 ; random MS: 0.85 )					Minepump model (all act. MS: 0.60 ; random MS: 0.82 )				
	<i>Live m.</i>	<i>Killed m.</i>	<i>FMM</i>	<i>Speedup</i>		<i>Live m.</i>	<i>Killed m.</i>	<i>FMM</i>	<i>Speedup</i>
Min.	57	21	20	1.1	Min.	441	43	26	1.7
Max.	442	154	83	5.3	Max.	623	212	64	9.7
Median	113	79	38	2.5	Median	533	108	41	8
Mean	120	78	39	2.5	Mean	530	100	42	7.6
S.Dev.	43	35	7.1	6.1	S.Dev.	35	49	6.5	34

Claroline model (all act. MS: 0.07 ; random MS: 0.27 )					AGE-RR model (all act. MS: 0.66 ; random MS: 0.27 )				
	<i>Live m.</i>	<i>Killed m.</i>	<i>FMM</i>	<i>Speedup</i>		<i>Live m.</i>	<i>Killed m.</i>	<i>FMM</i>	<i>Speedup</i>
Min.	40,314	236	26	9.1	Min.	598,520	5,644	39	140
Max.	103,346	4,091	19,282	5.4	Max.	3,948,806	99,754	46,839	84
Median	53,951	652	58	380	Median	910,000	9000	110	3,300
Mean	57,000	870	280	100	Mean	1.1e+06	14,000	200	2,900
S.Dev.	13,000	710	1,400	22	S.Dev.	590,000	12,000	790	870

Elsa-RR model (all act. MS: 0.75 ; random MS: 0.49 )					Elsa-RRN model (all act. MS: 0.77 ; random MS: 0.30 )				
	<i>Live m.</i>	<i>Killed m.</i>	<i>FMM</i>	<i>Speedup</i>		<i>Live m.</i>	<i>Killed m.</i>	<i>FMM</i>	<i>Speedup</i>
Min.	20,743	775	104	7.5	Min.	34,999	1,286	93	14
Max.	59,237	13,400	3,109	19	Max.	166,433	34,498	36,158	4.6
Median	22,676	918	191	89	Median	45,000	1,600	180	200
Mean	27,000	1,300	230	62	Mean	52,000	2,400	300	90
S.Dev.	8,500	1,500	170	84	S.Dev.	17,000	3,200	1,600	17

**Table 6: Mutant execution time in  $\mu$ -seconds**

Random Model (all act. MS: 0.16 ; random MS: 0.63 )				
	<i>Live m.</i>	<i>Killed m.</i>	<i>FMM</i>	<i>Speedup</i>
Min.	327,418	24,675	875	28
Max.	2,552,363	140,917	60,354	42
Median	1.3e+06	55,000	1,500	160
Mean	1.3e+06	63,000	1,800	370
S.Dev.	560,000	29,000	3,500	210

**Table 7: All-order mutation score. For each test set and model, the table records the number of possible mutants (# mut.), the number of live mutants after the test set execution (#Lv.), the mutations score (MS) and the SAT computation time (T) in seconds.**

Model	# mut.	All act.			Rand		
		#Lv.	MS	T	#Lv.	MS	T
S. V. Mach.	127	1	0.99	1.10	1	0.99	17.67
Minepump	8,388,607	1	>0.99	1.84	1	>0.99	15.72
Claroline	5.49e+303		Timeout			Timeout	
AGE-RR	4.71e+956		Timeout			Timeout	
Elsa-RR	1.46e+194	2916	>0.99	37.78	144	>0.99	10.19
Elsa-RRN	7.61e+286	36	>0.99	150.32	16	>0.99	83.04
Random	2.62e+2577		Mem. overflow			Mem. overflow	

used to generate test cases killing them in order to augment the test suite. Exploring all-order MS in selective mutation or test case generation scenarios are part of our future work.

#### 4.2.2 Threats to Validity

**Internal Validity:** Our experiments were performed on 7 models: 2 academic examples (the soda vending machine and the the mine pump), 4 larger real-world models (Claroline, AGE-RR, Elsa-RR, and Elsa-RRN) and a randomly generated one. These models come from different sources and represent different kinds of systems: embedded systems designed by an engineer and web-based applications where the model has been reverse-engineered from a running in-

stance. The random model was built upon a set of generated TSs in order to match the real system state-space measures, as described by Pelánek [56, 57].

**Construct Validity:** We chose to apply mutants for 1/10 of the states and/or transitions of the mutated model. This might result in more (or less) mutants than needed for the larger models. However, this is expected when using mutation. Additionally, since model-based mutation is applied to the system’s abstraction, abstract actions represent many concrete actions. It is therefore important to ensure a good coverage of most of the model actions.

TS and FTS executions are different, and do not use the same algorithms. In order to decrease the bias in measuring execution time, both executions of the models have been done using VIBeS [17], our *Variability Intensive Behavioural teSting framework* Java implementation. The two execution classes are different but use a variant of the same algorithm described in Section 3.2. Moreover, we used the *Stopwatch* Java class to measure the call to the execute method (i.e., model loading and result writing time have been omitted). Finally, we ran each test case 3 times on each mutant model (classical and FTS) to avoid bias due to process concurrency.

**External Validity:** We cannot guarantee that our results are generalizable to all behavioural models. However, we recall the diversity of the model sources (hand-crafted, reverse-engineered, and randomly generated to match real system state-space) as well as the diversity of considered systems.

## 5. RELATED WORK

Program mutation was proposed as a rigorous testing technique [12]. The idea was then applied to test specification models [50] and recently to resolve software engineering problems such as the improvement of non-functional properties [42], locating [53] and fixing software defects [43]. Here we briefly discuss works related to model-based mutation and testing, and code-based mutation.

## 5.1 Model-Based Mutation

The idea of model-based mutation has been elicited by Gopal and Budd [13] who called it “Specification Mutation”. Specification mutation promises to identify defects related to missing functionality and misinterpreted specifications [13]. This is desirable since these kinds of defects cannot be identified by any code-based testing technique [28,62], including code-based mutation.

Gopal and Budd [13] studied mutation for specifications expressed in logic. Similarly, Woodward [63] mutated and experimented with algebraic specifications. Mutating models like finite state machines and Statecharts has also been done by Fabbri *et al.* [21]. Hierons and Merayo [27] used Probabilistic Finite State Machines. All these studies suggested a set of operators and report some exploratory results. Amman *et al.* [4] suggested comparing the original and the mutated specification models using a model checker in order to generate counterexamples. These can then be used as test cases for the system under test. Black *et al.* [10] defined a set of operators based on empirical and theoretical analysis. They also defined a process of using them based on the SMV model checker. Contrary to our approach, none of these methods considers the mutation efficiency.

Recent research focuses on mutating behavioural models. Aichernig *et al.* [2,3] defined UML state machines mutant operators and used them to insert faults in the models of an industrial system. These were used to design tests. The approach has a formal ground but neither considers optimising the test execution, nor higher-order mutation. Belli and Beyazit [8,9] compare event-based and state-based model mutation testing. Both approaches were found to have similar fault detection capabilities. The authors also report that it seems more promising to perform higher-order mutation than first-order mutation but did not provide evidence in support of this argument. Krenn *et al.* [39] made available their MoMuT tool, but it is dedicated to test generation and not mutant execution as our approach. In their most recent work [38], they use an idea similar to FMM by triggering mutations during exploration of the model, avoiding execution of similar prefixes in different mutants. Additionally, MoMut does not support higher-order mutation.

Other applications of model-based mutation are to test model transformations and test configurations. Mottu *et al.* [47] defined a fault model relevant to the model transformation process based on which they propose a set of mutant operators. Henard *et al.* [26] define mutant operators for feature models. Along the same lines, Lackner and Schmidt [40] define mutant operators for the mappings of features with other model artifacts. Finally, Papadakis *et al.* [51] demonstrated that model-based mutation of the combinatorial interaction testing models has a higher correlation with the actual fault detection than the use of combinatorial interaction testing. Thereby, they provide ground to the argument that model-based mutation might be more effective than the other model-based testing methods.

## 5.2 Model-Based Testing

Offutt *et al.* [49] define test criteria for state-based specifications. They also describe techniques to automatically generate tests based on these criteria. Lackner *et al.* [41] suggested a test generation approach for product lines. Similar to our work they combine feature diagrams with state machines to handle the product line variability. However,

their approach does not perform mutation and it is specific to software product lines. Briand *et al.* [11] proposed a technique for generating tests from statecharts. Their results were validated through code-based mutation.

## 5.3 Code-Based Mutation

In the context of code-based mutation, executable mutants are needed. This introduces a compilation overhead which is proportional to the number of mutants. To reduce this cost, Untch *et al.* [60] proposed mutant schemata, an approach that replaces the program operators with schematic functions. These functions introduce the mutants at runtime and thus, only one compilation is needed. Ma *et al.* [45] suggested using bytecode translation, a technique that introduces the mutants directly at the bytecode level and thus avoid multiple compilations.

To reduce the test execution overhead, several optimizations have been proposed. Delamaro and Maldonado [16] suggested recording the execution trace of the original program and consider only the mutants that are reachable by each of the employed tests. Along the same lines, Mateo and Polo [46] suggested stopping mutant executions when they cause infinite loops. Jackson and Woodward [29] suggested parallelizing the mutant execution process. Kapoor and Bowen [35] proposed ordering the mutants in such a way that the test execution is minimized. Papadakis and Malevis [55] used mutant schemata to identify mutants that are reached and infected by the considered tests. They then reduce test execution by considering only the mutants that cause infection. This technique was later evaluated by Just *et al.* [32] who found that it reduces test execution by 40%.

## 6. CONCLUSION

This paper presents a family-based approach to model-based mutation testing, named Featured Mutant Model. It allows to generate mutants of any order and assess test effectiveness via an optimised execution scheme. Testing behavioural models with FMM is a completely automated process that involves no extra manual or computational effort over previous approaches.

In short, the use of FMM has the following benefits: (i) it can easily reason about and generate behavioural mutants, (ii) it can significantly speed up the evaluation of test suites against mutants (up to 1,000 times) and (iii) it can efficiently perform higher-order mutation. But, obviously, this is not the end of the story.

In our future work, we will further investigate scalability issues regarding all-order mutation analysis to be able to compute mutation score for the largest models. This implies the optimisation of the boolean formulas or approximate computation heuristics. Finally, since “mutants are a valid substitute for real faults” [33], we envision to develop test case generation techniques based on mutation coverage of the FMM.

## Acknowledgements

The authors would like to thank Maxime Cordy, Bernhard Aichernig, and the reviewers for their helpful comments, the AGE (University of Namur) and the Elsa organisation for providing logs of WordPress sites. This research was partly funded by Walloon region under the INOGRAMS project (n°7171). Mike Papadakis is supported by the National Research Fund, Luxembourg, INTER/MOBILITY/14/7562175.

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